

Group Code	Number	Name	Surname	Dept.	Project Subject
A	201726038	Türkan Simge	İŞPAK	EE	<ul style="list-style-type: none"> - Implementation of a 2D convolutional Layer function in C on a M4 Processor, with input arguments (stride, padding, filter size, etc) - Sending the resulting layer in UART to HyperTerminal and displayin the result (in MATLAB) - (bonus) getting an input from MATLAB via UART
A	201626015	Uğur Berk	ÇELİK	EE	
B	201414051	Arda	VARDAR	ECE	<ul style="list-style-type: none"> - Implementation of a 2D convolutional Layer function in C on a M4 Processor, with input arguments (stride, padding, filter size, etc) - Sending the resulting layer in UART to HyperTerminal and displayin the result (in MATLAB) - (bonus) getting an input from MATLAB via UART
B	201514203	Muhammet	BAĞOĞLU	ECE	
C	201626066	Furkan	UYSAL	EE	<ul style="list-style-type: none"> - Implementation of the MFFC function in C on a M4 Processor, with input argument MxNx3 image array - Sending the resulting layer in UART to HyperTerminal and displayin the result (in MATLAB) - (bonus) getting an input from MATLAB via UART
D	201626672	Ümit	UZAR	EE	<ul style="list-style-type: none"> - Implementation of a 2D template detection function in C on a M4 Processor, with input argument MxNx3 image array and outputs the coordinates of the template (shape of you choice, circle etc.) - Sending the resulting coordinates in UART to HyperTerminal and displayin the result (in MATLAB) - (bonus) getting an input from MATLAB via UART
D	201626418	Başar	ŞAHİN	EE	
E	201626020	Mert Anıl	DEMİRHAN	EE	<ul style="list-style-type: none"> - Implementation of the Laplacian Edge detection filter in C on a M4 Processor, with input argument MxNx1 grayscale image array and outputs the edge image. - Sending the resulting coordinates in UART to HyperTerminal and displayin the result (in MATLAB)
E	201626022	Mehmet Kaan	DÖNMEZ	EE	
F	201626009	Eren	AYDINGÜN	EE	<ul style="list-style-type: none"> - Implementation of the Sobel Edge detection filter in C on a M4 Processor, with input argument MxNx1 grayscale image array and outputs the edge image. - Sending the resulting coordinates in UART to HyperTerminal and displayin the result (in MATLAB) - (bonus) getting an input from MATLAB via UART
G	201626044	Ataberk	ÖZBERK	EE	TM4C123 Camera Interfacing
G	201626062	Mert	TOKTAŞ	EE	
?	201417008	Fatih	ÇETİN	MECE	no group yet
?	201417014	İbrahim	EKİCİ	MECE	no group yet
?	201417025	Muhammet Doğukan	KUYUMCU	MECE	no group yet